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Sentiment Analysis of Movie Reviews Using Machine Learning Techniques

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Abstract: Sentimental analysis is the analysis of opinions and emotions from any type of message or text. Sentimental analysis of the data is very helpful to convey the emotion of the majority or particular individual. It is also called opinion mining. This technique is performed to find the sentiment of the individual for a given source of content. Online platforms like social media contain a high volume of data in the form of reviews, tweets, comments, blogs, etc. This paper analyzes the movie reviews using various methods such as KNN, Naive Bayes, LSTM, and Random Forest Classifier.

Keywords: Dataset, Sentiment Analysis, Reviews, K-Nearest Neighbor, Naive Bayes.

I.INTRODUCTION

The Internet has evolved on such a large scale that everything can be controlled through the web because people want to share every part of their life on social media, which also includes their views on every single thing happening in the real world. Nowadays, the success or failure of a product is fully dependent on the reviews and satisfaction of consumers whether it be a new or already existing product. These opinions people share on social networking sites are generally known as Short Texts because of their length [1]. These short texts have taken over the traditional approaches because of the amount of the public getting influenced by them. This is why it is important to classify them based on how they're used (slang, sarcasm, sentiment, etc.).

The movie review is a popular way of doing an analysis of a movie and collectively determining whether the movie is worth recommending. The idiosyncrasy of a movie review is that it does not simply evaluate the movie but also gives the viewer the required aspect, which is the key foundation of the review. Reviews are posted by evaluating factors including plot, acting, dialogues, cinematography, and music. These reviews are shared and stored on various platforms and one of them is IMDB, which stores the data of every movie with summary, rating, and collective reviews from viewers. The task of Sentiment analysis mainly includes Preprocessing [2], Classification [3], and at last analysis of the results.

Sentiment analysis is the automated process of analyzing sentences to determine the sentiment formulated which can be either positive, negative, or neutral. These sentiments are evaluated based on emotions like happiness, sadness, agony, hated resentment, and affection.

Sentiment analysis is so efficient, and because of its accuracy it has numerous popular applications like:

• Social media monitoring. Social media posts often demonstrate some of the most honest views about products. Multiple tweets are posted every second and processing all of them manually will be troublesome. But, with the help of ML software, we can filter that data in a few minutes.

• **Customer feedback.** Sentiment analysis can also be used to gain intuitions from the collection of feedback available online.

Sentiment analysis will calculate whether the comment should be considered positive or negative.

• **Market and competitor research.** Sentiment analysis can also be used to find out who's trending among your competitors and how it can affect the market. It will analyze the competitor's data to find out what could work out for the public by understanding the strengths and weaknesses of both sides.

II.MACHINE LEARNING METHODS

A. DECISION TREE

It is the type of supervised machine learning algorithm and it is used for both classification and regression problems. It is a graph that uses tree-based methods to illustrate a tree's every possible outcome. It is a decision support tool and it uses a tree-like structure and its possible consequences.

It starts with a single node and branches off into other possibilities.



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Fig 3.1.1 A figure that represents different states of decision and what outcome should be generated as a result using conditions (yes/no).

B. NAIVE BAYES

It is a supervised machine learning algorithm, and it works based on Bayes' theorem. Naive Bayes uses conditional probability theorems to classify the data. Bayes classifiers will assume strong or naïve independence between attributes of data points. These methods are broadly used in text categorization-based problems as it is easy to implement. it is also known as independence Bayes.



 $P(c \mid \mathbf{X}) = P(x_1 \mid c) \times P(x_2 \mid c) \times \cdots \times P(x_n \mid c) \times P(c)$

Fig. 3.1.2 A figure that represents how to calculate posterior probability using different terms p(x|c) that means likelihood, p(c) means class prior probability and p(x) means predictor prior probability.

C. K-NEAREST NEIGHBOR

It is the simplest classification algorithm that attempts to determine how near the group of data points are.it used both classification and regression base problems.



Fig. 3.1.3 In the above representation there are 2 categories (category A and category B), where problem is that we have a new data point x1 that makes confusion that in which category a new data point lies? To solve this problem, we required a K-NN algorithm because K-NN easily identifies the category of a particular dataset.

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D. LSTM (LONG SHORT TERM MEMORY)

It is the revised version of a recurrent neural network. It is used for classification and attempts to predict the sentiment of the movie review.



Fig. 3.1.4 In the above figure LSTM contains feedback connections which make them different to more traditional feedforward neural networks that enable LSTMs to process entire sequences of data are being biased on each point in the list independently and LSTMs specifically focus on processing continuous data such as text, speech, and general time-series.

III. LITERATURE SURVEY

In paper [4] Joscha et. al, performed a comparison between various machine learning methods like a bag of words, ngrams for using semantic information to enhance the performance of sentiment analysis. In earlier approaches, there was no consideration of the semantic associations between sentences or documents. [5] neither paper 2, compared the different methodological variants nor provided the most favorable method to merge the disclosure units. They aimed to improve the sentiment analysis by using Rhetoric Structure Theory as it gives hierarchical representations at the document level. An integration grid search and weighting were proposed by them to find out the average scores of sentiments from the RST tree. To reduce the complexity of the RST tree, binary data was encoded into the random forest using feature engineering. Also, they gave the conclusion that ml raised the balanced accuracy and gave a high F1 score of 71.90%. In paper [6] Dhiraj Murthy provided what role is played by tweets in the political elections. Analysis of the sentences was done. Sentences that contain quantitative terms to classify. They were classified as opinionated or non-opinionated and identifications of the polarity were expressed using fuzzy set theory. The fuzzy base knowledge base was developed by interviewing various health center doctors. There was various research done in the field but they haven't considered the quantitative data contained in the reviews while analyzing the sentiment polarity of the review [6]. [7] In sentiment analysis, the challenging part is the opinion of words in a sentence there are situations when a word(sentence) is considered as positive and sometimes they are considered as negative this creates confusion whereas the traditional text processing considers that if there is a 2-bit change in the word then no change is considered. In paper [8] Ahmad Kamal, an opinion mining framework was designed that facilitates objectivity or subjectivity analysis, features extraction and reviews summarization, etc.

In paper [9], Researchers examined the prevalence and geographic variations for opinion polarities about e-cigarettes on Twitter. They collected data from Twitter by pre-defined seven keywords. They classified the tweets into four categories: Irrelevant to e-cigarettes, Commercial tweets, organic tweets with attitudes (supporting or against or neutral) the use of e-cigarettes, and the geographic locations information city and state. In paper [10], Akshay Amolik et. al. created the dataset using Twitter posts of movie reviews and related tweets about those movies. On tweets, Sentence level sentiment analysis was performed. In paper [11] Humera Shaniya et al. classified movie reviews for sentiment analysis using WEKA Tool. They enhanced the earlier work done in sentiment categorization analysis and categorized them as positive and negative.

PROPOSED METHOD

Sentiments are the opinion or view that is held and expressed. Sentiments (emotions) are of different types like positive, negative. There are many reasons why these sentiments can be positive or negative based on the attitude(likes or dislikes) of the person giving the movie review. We have employed the LSTM algorithm in the suggested system to identify the sentiment of the movie review.



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A. Dataset

This collection contains 50k movie reviews and the associated sentiment which is either positive or negative. The dataset have been collected from IMDB movie reviews(comments).

۹		bas df df.	e_csv = r' <u>/con</u> = pd.read_csv(head()	tent/drive/MyDr base_csv)	<u>ive/Colab</u> No	tebooks/IMD	B Dataset.csv'	
{ <i>x</i> }					review	sentiment		
		0	One of the other	reviewers has mer	ntioned that	positive		
		1	A wonderful lit	tle production. <br< td=""><td>/> The</td><td>positive</td><td></td><td></td></br<>	/> The	positive		
		2	I thought this w	as a wonderful way	y to spend ti	positive		
		3	Basically the	ere's a family where	e a little boy	negative		
		4	Petter Mattei's	"Love in the Time of	of Money" is	positive		
		X,y x_t pri pri	= df['review' rain,x_test,y_ nt(x_train.sha nt(x_test.shap].values,df['se train,y_test = pe) e)	ntiment'].va train_test_s	lues plit(X,y,st	ratify=y)	
		(37 (12	500,) 500,)					

Fig:2 DATASET BREAKUP (TABLE I) DATASET IMAGES

B. Preprocessing

Data Pre-Processing plays a very important role in machine learning. It transforms raw data into a useful data format. Commonly it is the primary step to clean the data. Data Pre-Processing transforms the data into a format which is more easy and error free processing for the classification. The dataset is first processed to remove the null attributes and the records that contain the NA attributes.

After that we will process the sentences. we will be performing tokenization i.e sentences will be broken into smaller parts called as tokens and we will be removing the stopwords like is, are, the etc.

Next step will be performing padding operations. It will help to make the length of the sentences equal.

All the experiments are run over a set of train and test data.

<pre>def preprocess_string(s): s = re.sub(r"[^\w\s]", '', s) s = re.sub(r"\s+", '', s) s = re.sub(r"\d", '', s)</pre>
return s def tockenize(x_train,y_train,x_val,y_val): word_list = []
<pre>stop_words = set(stopwords.words('english')) for sent in x_train: for word in sent.lower().split(): word = preprocess_string(word) if word not in stop_words and word != '': word_list.append(word)</pre>
corpus = Counter(word_list)
<pre>corpus_ = sorted(corpus,key=corpus.get,reverse=True)[:1000]</pre>
<pre>onehot_dict = {w:i+1 for i,w in enumerate(corpus_)}</pre>
<pre>final_list_train,final_list_test = [],[] for sent in x_train: final_list_train.append([onehot_dict[preprocess_string(word)] for word in sent.lower().split()</pre>
encoded_train = [1 if label =='positive' else 0 for label in y_train] encoded_test = [1 if label =='positive' else 0 for label in y_val] return np.array(final_list_train), np.array(encoded_train),np.array(final_list_test), np.array(encoded_test),onehot_dict
<pre>[] x_train,y_train,x_test,y_test,vocab = tockenize(x_train,y_train,x_test,y_test)</pre>

we split the dataset into train and test to get the information how our model performs on unseen data. The ratio of split is 80-20. 80% of the total is train and 20% contains testdata.



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C. Feature Selection

It is one the most important steps, here we will select the features that will increase the efficiency of the model.

D. Model Selection And Training

We have employed LSTM as the machine learning algorithm that will be used and we will perform training of the model on the dataset. LSTM basically refers to long short term memory. It helps to store the important words in its memory that will help to predict the sentiment.

D	class S def	entimentRNN(nn.Module): init(self,no_layers,vocab_size,hidden_dim,embedding_dim,drop_prob=0.5): super(SentimentRNN,self)init()	
		self.output_dim = output_dim self.hidden_dim = hidden_dim	
		<pre>self.no_layers = no_layers self.vocab_size = vocab_size</pre>	
		<pre># embedding and LSTM layers self.embedding = nn.Embedding(vocab_size, embedding_dim)</pre>	
		<pre>#lstm self.lstm = nn.LSTM(input_size=embedding_dim,hidden_size=self.hidden_dim,</pre>	
		<pre># dropout layer self.dropout = nn.Dropout(0.3)</pre>	
		<pre># linear and sigmoid layer self.fc = nn.Linear(self.hidden_dim, output_dim) self.sig = nn.Sigmoid()</pre>	
	def	<pre>forward(self,x,hidden): batch_size = x.size(0) # embeddings and lstm_out embeds = self.embedding(x) # shape: B x S x Feature since batch = True #print(embeds.shape) #[50, 500, 1000] lstm_out, hidden = self.lstm(embeds, hidden)</pre>	
		<pre>lstm_out = lstm_out.contiguous().view(-1, self.hidden_dim)</pre>	
		<pre># dropout and fully connected layer out = self.dropout(lstm_out) out = self.fc(out)</pre>	
		<pre># sigmoid function sig_out = self.sig(out)</pre>	
		<pre># reshape to be batch_size first sig_out = sig_out.view(batch_size, -1)</pre>	
		<pre>sig_out = sig_out[:, -1] # get last batch of labels</pre>	
		<pre># return last sigmoid output and hidden state return sig_out, hidden</pre>	

Shape:

- Input: $(N, C_{in}, H_{in}, W_{in})$
- Output: $(N, C_{out}, H_{out}, W_{out})$ where

$$\begin{split} H_{out} &= \left\lfloor \frac{H_{in} + 2 \times \mathrm{padding}[0] - \mathrm{dilation}[0] \times (\mathrm{kernel_size}[0] - 1) - 1}{\mathrm{stride}[0]} + 1 \right\rfloor \\ W_{out} &= \left\lfloor \frac{W_{in} + 2 \times \mathrm{padding}[1] - \mathrm{dilation}[1] \times (\mathrm{kernel_size}[1] - 1) - 1}{\mathrm{stride}[1]} + 1 \right\rfloor \end{split}$$

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E. Prediction

Once the model is trained we will be performing the prediction on the unseen data and checking whether the predicted sentiment is correct or not.

D	<pre>[] def predict_text(text): word_seq = np_array[[wcad]preprocess_string[word]) for word in text.split() if preprocess_string[word] seq_axis=n) psd = turch_from_mmy(sabling_word_seq_axis=n) imputs = psd.tu(serice) betch_siz= 1 h = model_presi.shit_hidden(betch_size) h = tuple((text.sets for each in %)) output, h = model_pres(imputs, h) return(watput.item())</pre>
	<pre>index = 30 print(ff(reciar)[index]) print('='78) print('='78) print('='78) pro = predict_tett(df('reciar)[index])') status = yositifte'' if pro > 0.5 cise 'negative'' yro = (1 - yro) if status = 'negative'' cise pro print('='nedicted sentement is (status) with a probability of (pro)')</pre>
	at and organically grigping. Edward Dmytryk's CrossFire is a distinctive suspense thriller, an unlikely "message" movie using the look and devices of the noir cycle.dr //dr //Bivowacked in Washington, DC, a company of soldiers cope with their restlessness by banging out in bars.
	<pre>content is positive with a probability of 0.4093405413034 Predicted sentiment is positive with a probability of 0.4093405413034 /usr/local/lib/pythob3.7/dit-packages/tor/m/m/modules/mm.pyt82: UserWarning: RN module weights are not part of single contiguous chunk of memory. This means they need to be compacted at every call, possibly greatly increasing memory usage. To compact weights again call flattery /usr/local/lib/pythob3.7/dit-packages/tor/m/m/modules/mm.pyt82: UserWarning: RN module weights are not part of single contiguous chunk of memory. This means they need to be compacted at every call, possibly greatly increasing memory usage. To compact weights again call flattery /usr/local/lib/pythob3.7/dit-packages/tor/m/m/modules/mm.pyt82: UserWarning: RN module weights are not part of single contiguous chunk of memory. This means they need to be compacted at every call, possibly greatly increasing memory usage. To compact weights again call flattery /usr/local/lib/pythob3.7/dit-packages/tor/m/m/modules/mm.pyt82: UserWarning: RN module weights are not part of single contiguous chunk of memory. This means they need to be compacted at every call, possibly greatly increasing memory usage. To compact weights again call flattery /usr/local/lib/pythob3.7/dit-packages/tor/m/m/modules/mm.pyt82: UserWarning: RN module weights are not part of single contiguous chunk of memory. This means they need to be compacted at every call, possibly greatly increasing memory usage. To compact weights again call flattery /usr/local/lib/pythob3.7/dit=packages/tor/m/m/modules/mm.pyt82: UserWarning.</pre>

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Flask Web App

After we've created this model, we'll build a flask web application and deploy it to the cloud.

IV. EXPERIMENTATION AND RESULT

As discussed above, we have tried multiple classification algorithms like Decision tree, Naive Bayes, KNN, LSTM on our movie review dataset containing movie reviews and associated sentiment. While working we can get a result that LSTM showed the best result among the tiered algorithms and KNN showed the worst result approximately 60%. The accuracy was in order LSTM> Naive Bayes > Decision Tree> KNN. When we found that the accuracy of LSTM was higher than others, we tried hyper tuning of parameters like learning rate, number of epochs. When we tried the number of epochs = 5 and learning rate as 0.1 accuracy was 86% and when hyper tuned the parameter and put epochs=10 and learning rate =0.01 accuracy came out 90.9%.

	LSTM	Naive Bayes	Decision Tree	KNN
Bag of words of 10,000	85.1	81.5	79.7	46.7
Bag of 50,000	90.9	85	82	60

Bag of 10,000 words and Bag of 50,000 words



In the above graph, we have made a comparison between different algorithms on different amounts of words and we concluded when we increased the number of words LSTM performed well. While training our model on LSTM we also performed some hyper tuning of parameters like learning rate and several epochs etc.

Experiment





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Sample input:



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	Class Sentiment (MM (MILPODULE):	
	<pre>definit(self,no_layers,vocab_size,hidden_dim,embedding_dim,drop_prob=0.5 super(SentimentRNN.self). init ()</pre>	i):
	self.output_dim = output_dim self.hidden_dim = hidden_dim	
	<pre>self.no_layers = no_layers self.vocab_size = vocab_size</pre>	
	<pre># embedding and LSTM layers self.embedding = nn.Embedding(vocab_size, embedding_dim)</pre>	
	<pre>#lstm self.lstm = nn.LSTM(input_size=embedding_dim,hidden_size=self.hidden_dim, num_layers=no_layers, batch_first=True)</pre>	
	<pre># dropout layer self.dropout = nn.Dropout(0.3)</pre>	
	<pre># linear and sigmoid layer self.fc = nn.Linear(self.hidden_dim, output_dim) self.sig = nn.Sigmoid()</pre>	
	<pre>def forward(self,x,hidden): batch_size = x.size(0) # embeddings and lstm_out embeds = self.embedding(x) # shape: 8 x S x Feature since batch = True</pre>	
	<pre>#print(embeds.shape) #[50, 500, 1000] lstm_out, hidden = self.lstm(embeds, hidden)</pre>	
	<pre>lstm_out = lstm_out.contiguous().view(-1, self.hidden_dim) # dropout and fully connected layer</pre>	
	<pre>out = self.dropout(lstm_out) out = self.fc(out)</pre>	
	<pre># sigmoid function sig_out = self.sig(out)</pre>	
	<pre># reshape to be batch_size first sig_out = sig_out.view(batch_size, -1)</pre>	
	<pre>sig_out = sig_out[:, -1] # get last batch of labels</pre>	
	# return last sigmoid output and hidden state return sig_out, hidden	
. <u>΄</u> α	[] clip = 5 epochs = 7 valid loss min = np.Inf	
 ح (۲۶)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc_erech_vl_acc_= [] []</pre>	
(.) (x)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs):</pre>	
 Q (X)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_losses = [0] train_acc = 0.0</pre>	
 Q (X)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_v1_loss = [],[] epoch_tr_acc,epoch_v1_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state</pre>	
(x)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader:</pre>	
(x)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise</pre>	
Q (X)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.ran() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h])</pre>	
 Q (X)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h)</pre>	
	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float())</pre>	
 Q (X)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float()) loss.backward() train_losses.anpend(loss.item())</pre>	
	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float()) loss.backward() train_losses.append(loss.item()) # calculating accuracy train_losses.item()) # calculating accuracy train_train_train_trained the state train_losses.item()) # calculating accuracy train_trained the state train_trained the state trained the state s</pre>	
	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output_h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float()) loss.backward() train_losses.append(loss.item()) # calculating accuracy accuracy = acc(output,labels) train_acc += accuracy</pre>	
 (x)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float()) loss.backward() train_losses.append(loss.item()) # calculating accuracy accuracy = acc(output,labels) train_acc += accuracy # clip_grad_norm helps prevent the exploding gradient problem in RNNS / mo.utils.clip grad_norm (model.parameters(), clip)</pre>	LSTMs.
- Q (X)	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] epoch_tr_acc,epoch_vl_acc = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels in train_loader: inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float()) loss.backward() train_losses.append(loss.item()) # calculating accuracy accuracy = acc(output,labels) train_acc += accumacy #'clip_grad_norm' helps prevent the exploding gradient problem in RNMs (nn.utils.clip_grad_norm_(model.parameters(), clip) optimizer.step()</pre>	LSTMs.
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	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.intain() # initialize hidden state h = model.init_hidden(batch_size) for inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float()) loss.backward() train_losses.append(loss.item()) # calculating accuracy # ccliculating accuracy # ccliculating accuracy # cliculating accuracy # clip_grad_norm helps prevent the exploding gradient problem in RNNs / m.utils.clip_grad_norm (model.parameters(), clip) optimizer.step() val_h = model.init_hidden(batch_size) val_losses = [] val_acc = 0.0 val_d accuracy = 0.0 val_baccuracy = 0.0 val_baccuracuracy = 0.0 val_baccuracuracy = 0.0</pre>	LSTMs.
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	<pre>[] clip = 5 epochs = 7 valid_loss_min = np.Inf epoch_tr_loss,epoch_vl_loss = [],[] for epoch in range(epochs): train_losses = [] train_acc = 0.0 model.train() # initialiden state h = model.init_hidden(batch_size) for inputs, labels = inputs.to(device), labels.to(device) # Creating new variables for the hidden state, otherwise # we'd backprop through the entire training history h = tuple([each.data for each in h]) model.zero_grad() output,h = model(inputs,h) # calculate the loss and perform backprop loss = criterion(output.squeeze(), labels.float()) loss.backward() train_losses.append(loss.item()) # calculating accuracy accuracy = acc(output_labels) train_acc += accuracy # clip_grad_norm_(model.parameters(), clip) optimizer.step() val_h = model.init_hidden(batch_size) val_acc = 0.0 model.exel() for inputs, labels in valid_loader: val_h = tuple([each.data for each in val_h])</pre>	LSTMs.

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≔	+ Code + Text	
≣ α (£)	<pre>[] epoch_train_loss = np.mean(train_losses) epoch_val_loss = np.mean(val_losses) epoch_val_loss = np.mean(val_losses) epoch_train_acc = train_acc/len(train_loader.dataset) epoch_val_acc = val_acc/len(valid_loader.dataset) epoch_tr_loss.append(epoch_train_loss) epoch_tr_acc.append(epoch_val_loss) epoch_tr_acc.append(epoch_val_acc) print(f'train_loss : (epoch_train_acc)val_loss;') print(f'train_loss : (epoch_train_acc*100) val_accuracy : (epoch_val_acc*100)') if epoch_val_loss = valid_loss_min: torch.save(model.state_dict(), './state_dict.pt') print(validation loss decreased ((:.6f)> (:.6f)). Saving model'.format(valid_loss_min,epoch_val_loss)) valid_loss_min = epoch_val_loss print(25*'==')</pre>	
	Epoch 1 train_loss: 0.5194273465275765 val_loss: 0.4437732826471329 train_accuracy: 74.138666666666667 val_accuracy: 79.656 Validation loss decreased (inf> 0.443773). Saving model ==================================	
	Valuation loss decreased (0.3380> 0.33629). Javing model Epoch 4 train_accuracy : 87.2986666666666 val_accuracy : 85.976 Validation loss decreased (0.338209> 0.336231915907116 train_accuracy : 87.2986666666666 val_accuracy : 85.976 Validation loss decreased (0.338209> 0.336231). Saving model Epoch 5 train_loss : 0.2696306763291359 val_loss : 0.3324641445279121 train_accuracy : 88.752 val_accuracy : 85.824	
\diamond	Validation loss decreased (0.336234> 0.332464). Saving model Epoch 6 train_loss : 0.23086624428629876 val_loss : 0.35006691724061967 train_accuracy : 90.6453333333333333 val_accuracy : 85.768 Epoch 7	
	train_loss : 0.17408675122261047 val_loss : 0.384448705136776 train_accuracy : 93.22399999999999 val_accuracy : 84.736	
>_		



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D	<pre>[] def predict_text(text): word_seq = np.array([wcad][preprocess_string[word]] for word in text.split()</pre>
	<pre>index = 30 print(6f('review')[index]) print('='780 print('='780 pro = predict_text(6f('review')[index])') pro = predict_text(6f('review')[index]) status = 'positive' if pro > 0.5 else 'negative' pro = (1 - pro) if status == 'negative' else pro print('Predicted sentiment is (status) with a probability of (pro)')</pre>
	Taut and organically gripping, Edward Dmytryk's CrossFire is a distinctive suspense thriller, an unlikely "message" movie using the look and devices of the noir cycle. Or />Or />Bivouacked in Hashington, DC, a company of soldiers cope with their restlessness by Hanging out in bars.
	Actual sentiment is ; positive
	Predicted sentiment is positive with a probability of 0.99914554138184 /usr/local/lib/pythond.7/dist-packages/torch/m/modules/rm.py:682: UserWarning: NN module weights are not part of single contiguous chunk of memory. This means they need to be compacted at every call, possibly greatly increasing memory usage. To compact weights again call flatten_s self.dropout, self.training, self.bidirectional, self.batch_first)

V. CONCLUSION

In this research, various methods were used to find the sentiments of the movie reviews. The algorithms performed were LSTM, KNN, Naïve Bayes, Decision Tree. The finest results were given by the LSTM. The LSTM classifier achieved 90.90% accuracy, the Naïve Bayes classifier achieved 85% accuracy, the Decision Tree classifier achieved 80.2% accuracy, and the KNN classifier achieved 60% accuracy.

As of now, only a few algorithms have been tested, it is necessary to test other algorithms or create mixed methods to increase the accuracy of the results. Finding the sentiments of the reviews can help in a variety of domains. Smart systems can be developed which can provide the users with a complete overview of movies, products, services, etc. without requiring the user to review individual reviews, he or she can make direct decisions based on the results provided by the smart systems.

VI. ACKNOWLEDGEMENT

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