



SURVEILLANCE ROBOTIC CAR WITH LIGHTING SYSTEM

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Abstract: Spying literally way to watch from a distance. in this task, the paintings of designing and implementing manner of an Android primarily based secret agent robotic is described .the primary reason in the back of growing this robot is for the surveillance of human sports inside the conflict subject or get to realize about the state of affairs if a disaster happens, to decrease the risk of a lifestyles .The robot along with camera can wirelessly transmit actual time video with night time vision abilities, and with multi-sensor capabilities .This robotic is used to collect information from the far off terrain and reveal that information at a miles cozy vicinity with the help of IOT era. it's far widely used due to its simplicity and capability to regulate to fulfill alternate of wishes. The video transmission is practically achieved via high-speed photo transmissions. The robot will serve an appropriate system for the defense quarter and will also prevent unlawful activities.The robotic will help the police or navy/military to recognize the situation of the territory earlier than getting into it.

Keywords: Arduino, Spying Robot, LCD sensor, Montor, WiFi Control.

I. INTRODUCTION

Robots have become a platform to increase or discover a device to ease the paintings of human. A robotic basically is an intelligent tool designed to assist people in almost each relevant or irrelevant area. The robots haven't any fixed form, neither are been specific for any unique field or for any specific paintings. They may be made or transformed into any shape relying upon the place of application. most likely, these days robots are made with the assist of extra technology like as opposed to connection orientated; robots are being constructed with a complete connection less reason i.e. wireless ones.also with the help of surveillance cause, exceptional conditions, areas describing numerous problems may be monitored without problems. hence to decorate those functions in a better way, we've got carried out a wireless surveillance robot to screen environmental situations in an efficient way.

1.1 OBJECTIVE

The present gadget includes a robotic which matches identical like other conventional robots and feature quite a few drawbacks, such that a robot works inside unique method of technology, false reliable and so forth.the present system is very prone to get in touch with place facing difficulties and no fulfilled mechanism is available. it is also very time ingesting to address the difficulty and solve the same .In our proposed piece of work, the robot fulfills the problems given above. it's far very beneficial for tracking in areas where there is no internet connection and additionally the disintegrate of the conversation machine at some stage in any catastrophe.

1.2 SCOPE

- It could be used for spying reason.
- It may be used for surveillance purpose, each day and night time.
- It may also be used at some stage in catastrophe situations.
- It can be managed the use of any cell telephones.
- It lessen the chance of human life and will prevent illegal sports.
- It may be used to do the work which are not possible by way of humans.

II. ANALYSIS

2.1 SYSTEM ANALYSIS

2.1.1 Existing System

- Earlier robotic car was only used for driving or racing purpose.
- The communication between the receiver and transmitter is not accuracy or stable.



- Range of transmitting the signal is low
- The battery used in the existing system is non-reusable.
- This model can be accessed using either computer application or transmitter joy stick

2.1.2 Proposed system

- It can be used for both surveillance and patrolling the area.
- The improved version of camera is used in the robot for clear and high-quality video transmission.
- With internet facility it can be controlled using a browser itself with the help of URL.
- Lighting system is also used in this model for better video delivery.
- Communication between the transmitter and receiver is stable and can be controlled for long range.

III. BLOCK DIAGRAM

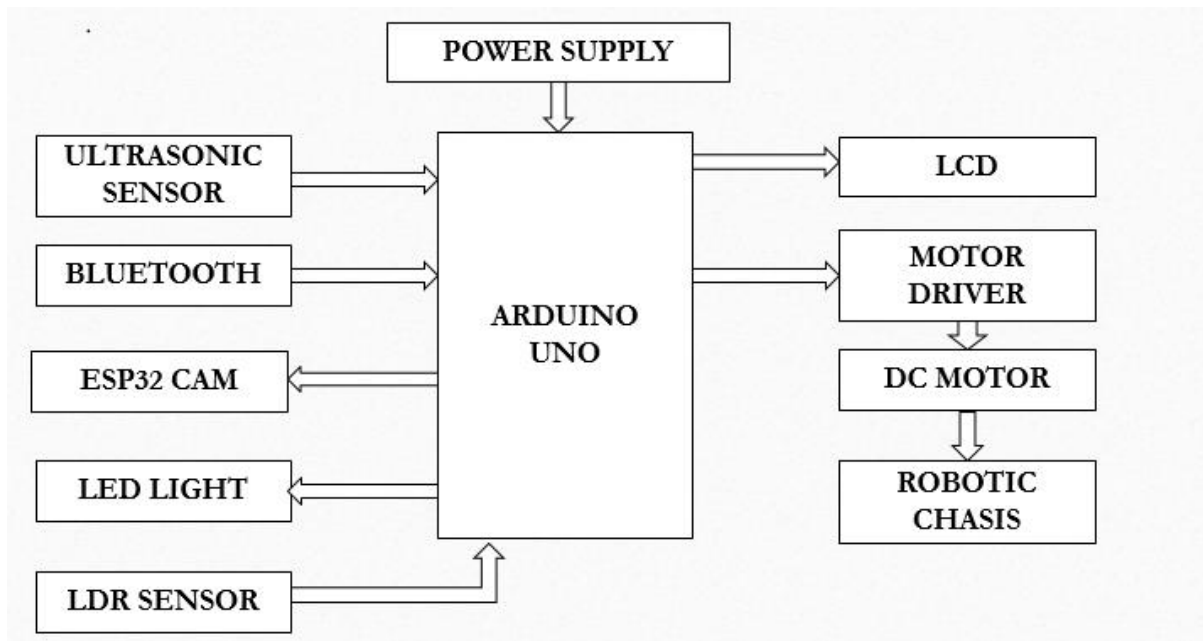


Figure 1.Overall Block Diagram

III. COMPONENTS

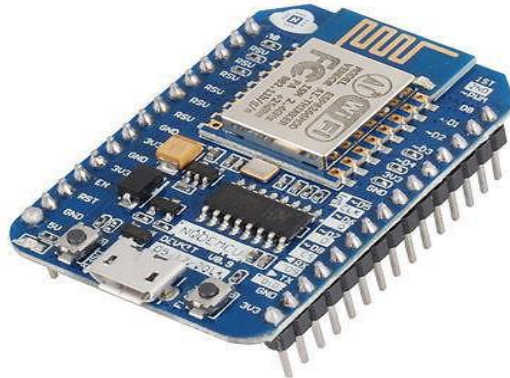
- Arduino uno
- Power supply
- Ultrasonic sensor
- Bluetooth
- Esp32 cam module
- Led light
- LCD
- Motor driver module
- Dc motors
- Robotic chassis
- LDR sensor

4.1 ARDUINO UNO :

Arduino is a device for making computer systems which can feel and manage extra of the bodily global than your pc computer. it's an open-deliver physical computing platform based totally totally on a easy microcontroller board, and a improvement surroundings for writing software application for the board. Arduino may be used to expand interactive objects, taking inputs from a diffusion of switches or sensors, and controlling a spread of lighting fixtures, automobiles, and other physical outputs. Arduino tasks may be stand-on my own, or they may be communicate with software program taking walks to your computer. The boards can be assembled by using manner of hand or bought preassembled; the open-



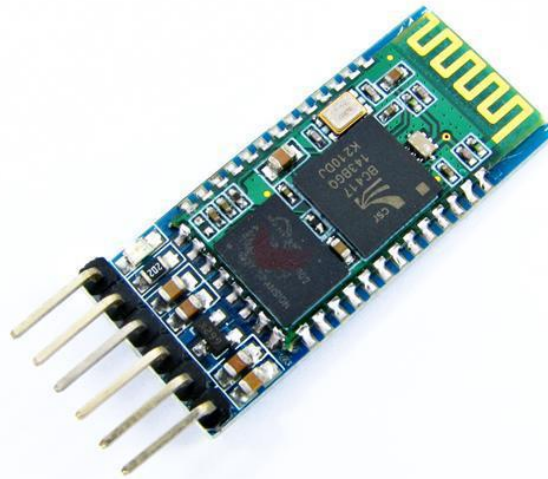
source IDE may be downloaded without cost. The Arduino programming language is an implementation of Wiring, a comparable physical computing platform, which is primarily based at the Processing multimedia programming environment.



4.2 BLUETOOTH

- It is used for many applications like wireless headset, game controllers, wireless mouse, wireless keyboard and many more consumer applications.
- It has range up to <100m which depends upon transmitter and receiver, atmosphere, geographic & urban conditions.
- It is IEEE 802.15.1 standardized protocol, through which one can build wireless Personal Area Network (PAN). It uses frequency-hopping spread spectrum (FHSS) radio technology to send data over air.
- It uses serial communication to communicate with devices. It communicates with microcontroller using serial port (USART).

HC-05 Bluetooth Module



4.3 ESP32 CAM MODULE

The ESP32-CAM is a small length, low energy intake digital camera module based totally on ESP32. It comes with an OV2640 digicam and offers onboard TF card slot. The ESP32-CAM may be widely used in shrewd IoT packages including wireless video tracking, WiFi image upload, QR identification, and so on.

4.3.1 Features

- Onboard ESP32-S module, supports WiFi + Bluetooth
- OV2640 camera with flash
- Onboard TF card slot, supports up to 4G TF card for data storage
- Supports WiFi video monitoring and WiFi image upload
- Supports multi sleep modes, deep sleep current as low as 6mA
- Control interface is accessible via pin header, easy to be integrated and embedded into user product.



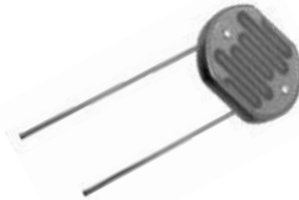
4.3.2 Applications

The ESP32-CAM suit for IOT applications such as:

- Smart home devices image upload
- Wireless monitoring
- Intelligent agriculture
- QR wireless identification
- facial recognition

LED LIGHT SENSORS

Light Sensors are photoelectric devices that convert light electricity (photons) whether or not seen or infra-crimson light into an electrical (electrons) sign A mild Sensor generates an output sign indicating the depth of mild by way of measuring the radiant electricity that exists in a very slender range of frequencies basically known as “light”, and which degrees in frequency from “Infra-purple” to “visible” as much as “Ultraviolet” light spectrum. The mild sensor is a passive devices that convert this “mild energy” whether or not seen or in the infra-purple components of the spectrum into an electrical sign output. light sensors are more usually called “Photoelectric devices” or “photograph Sensors” due to the fact the convert mild strength (photons) into electricity (electrons).



4.5 ULTRASONIC SENSORS OR ULTRASOUND SENSORS

Bats are excellent creatures. Blind from the eyes and yet a vision so unique that would distinguish between a moth and a damaged leaf even when flying at full pace. no question the vision is sharper than ours and is plenty beyond human abilities of seeing, but is genuinely no longer beyond our knowledge. Ultrasonic ranging is the approach utilized by bats and plenty of different creatures of the animal state for navigational purposes. In a bid to mimic the approaches of nature to acquire an area over the whole lot, we human beings have now not handiest understood it however have correctly imitated a number of these manifestations and harnessed their ability to the finest extent.

V. SOFTWARE REQUIREMENTS

5.1 ARDUINO IDE

The Arduino included improvement surroundings - or Arduino software (IDE) - contains a textual content editor for writing code, a message region, a text console, a toolbar with buttons for not unusual functions and a sequence of menus. It connects to the Arduino hardware to add programs written using Arduino software program software (IDE) are referred to as sketches. these sketches are written inside the text editor and are saved with the document extension.in. The editor has features for reducing/pasting and for searching/replacing textual content. The message location gives comments even as saving and exporting and additionally shows errors. The console displays textual content output via the Arduino software program (IDE), which includes entire errors messages and specific information. The bottom righthand nook of the window shows the configured board and serial port. The toolbar buttons permit you to affirm and upload packages, create, open, and hold sketches, and open the serial display screen. and speak with them.

VI. RESULT AND DISCUSSION

Surveillance robot can be designed to supply a reasonable stage of performance and ease, offering each consumer with a streamlined person experience. The surveillance robotic is aimed at offering tracking inclusive of vision, motion. The surveillance robot may be customized to fuse seamlessly to any warehouse, cross down or multi dwelling units. primarily based on modular designs and whole scalability, the surveillance robotic is designed to be expandable and permit for future manage enhancements, for this reason enhancing the accessibility of the consumer and offering a green manner out of the subculture device.

**VII . CONCLUSION**

The implementation of this work concludes that most important environmental catastrophes can be analyzed and solved in every relevant or beside the point discipline. With the extra features and technology, this robot can be stated as a reliable piece of paintings in every means of generation.

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