



BRAIN TUMOUR DETECTION USING CONVOLUTIONAL NEURAL NETWORK

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Abstract: Medical imaging automated fault identification is an area that is expanding in various diagnostic medical applications. Automated tumour detection in MRI is essential because it provides details on aberrant tissues required for treatment formulation. Human evaluation is the common technique for identifying errors in computed tomography brain pictures. This strategy is not practical due to the volume of data. As a result, creating precise and automated classification techniques is necessary to lower the rate of human mortality. Automated cancer detection methods are thus created since they would free up radiologist time and have a proven track record of accuracy. MRI brain tumour identification is a challenging endeavour due to the complexity and variety of tumours. We recommend applying machine learning techniques in this work to detect tumours in brain MRIs in order to overcome the limitations of the present classifiers. It is feasible to precisely identify cancer central nervous system using MRI by using computer learning and image classifiers.

INTRODUCTION

One of the most dangerous medical disorders is a brain tumour. The radiologist's first priority during the initial stages of cancer advancement is a complete and successful analysis. For determining the grade of a brain tumour, the histological grading approach, which is based on a stereotactic biopsy test, is the industry standard and accepted practise. The neurosurgeon has to make a tiny hole in the skull to extract tissue for the biopsy operation. The biopsy procedure carries a number of risks, including the potential for brain infections and tumour bleeding, which can result in seizures, excruciating headaches, stroke, comas, and even death. The primary issue with stereotactic biopsy, however, is that it is not 100 percent reliable, which could lead to a major diagnosis error and subpar therapeutic management of the ailment. Because it might be difficult for patients with brain cancers to undergo tumour biopsies, non-invasive imaging methods like magnetic resonance (MRI) have gained popularity for diagnosing brain tumours. Thus, it has become vital to develop algorithms for MRI data-based tumour grade identification and forecasting. However, when utilising an imaging technology like magnetic resonance imaging, it can be difficult to clearly see the tumour cells and distinguish them from the nearby soft tissues (MRI). The volume and diversity of tumours, including their unstructured shapes, substantial sizes, and unpredictable locations, can contribute to this, as can low light in imaging modalities, a great volume of data, or all of the above. Machine learning-based automated fault detection in medical imaging is a subject that is gaining popularity across many diagnostic applications. Its use in the MRI diagnosis of brain tumours is essential since it offers information about aberrant tissues required for treatment planning. Recent research suggests that automated computerised disease diagnosis based on medical image analysis may be a good option because it would free up the radiologist's time and offer proven accuracy. By sparing doctors from having to physically display tumours, computer algorithms that could provide precise and quantitative measures of tumour representation would also significantly benefit in the therapeutic treatment of brain tumours.

LITERATURE SURVEY

1. Sivaramkrishnan And Dr. M. Karnan "A Novel Based Approach for Extraction Of Brain Tumor In MRI Images Using Soft Computing Techniques," *International Journal Of Advanced Research In Computer And Communication Engineering*, Vol. 2, Issue 4, April 2013. A. Sivaramkrishnan et al. (2013) [1]

The Fuzzy Capproach clustering algorithm and histogram equalisation were used to create an image that portrayed the location of the brain tumour creatively and accurately. Primary factor assessment can be used to decompose images and shrink the wavelet coefficient. The predicted FCM clustering technique successfully removed the tumour from the MR images.

2. Asra Aslam, Ekram Khan, M.M. Sufyan Beg, *Improved Edge Detection Algorithm for Brain Tumor Segmentation, Procedia Computer Science*, Volume 58,2015, Pp 430-437, ISSN 1877-0509. M. M. Sufyan et al. [2] has developed a brain tumour segmentation technique based mostly on Sobel feature identification and an improved edge algorithm. The work they just presented uses a secure contour method to link the binary thresholding operation to the



Sobel approach and excavates various extents using different methods. After that process is finished, intensity measurements are used to distinguish cancer cells from the collected image.

3. **B.Sathya and R.Manavalan, Image Segmentation by Clustering Methods: Performance Analysis, International Journal of Computer Applications (0975 – 8887) Volume 29– No.11, September 2011. Sathya et al. (2011) [3],**

K-means, Improved K-means, C-means, and improved C-means algorithms are only a few examples of clustering algorithms. In their paper, they discussed an experimental analysis for sizable datasets made up of unique images. They looked at the results using several parametric tests.

BACKGROUND ANALYSIS

It uses state-of-the-art results in image classification based on transfer learning techniques to categorise the 1.2 million high-resolution images entered in the ImageNet LSVRC-2010 competition into the 1000 separate classes. Its top-1 and top-5 error rates on the test data were 37.5 percent and 17.0 percent, respectively, which was significantly better than the prior state-of-the-art. A different version of this model was also submitted to the ILSVRC-2012 competition, where it won with a top-5 test error rate of 15.3 percent, beating out the second-best entry's 26.2 percent. Five convoluted layers, some of which were followed by max-pooling layers, three fully connected layers, and a final 1000-way SoftMax made up the neural network, which had 60 million parameters and 650,000 neurons. It employed quasi synapses and a very effective GPU convolution operation implementation to speed up training. It has lesser precision and requires more computation time despite using high hardware complexity.

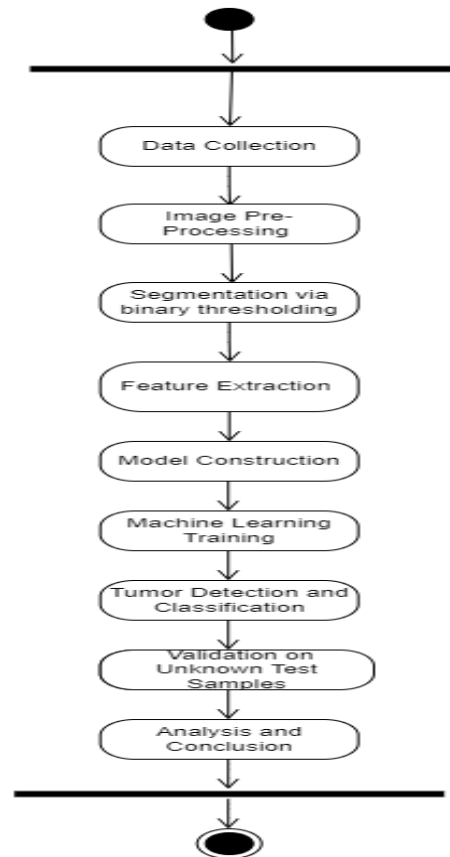
PROPOSED METHODOLOGY

16,384 pixels, or 128 by 128 pixels, make up the images of the brain tumours. Each neuron in the first layer receives a single pixel as input. Channels link the neurons in one layer to those in the subsequent layer. Each of these channels is given a weight, which is a numerical value. The sum of the inputs is transmitted as input to the neurons in the hidden layer after being multiplied by the corresponding weight. The bias, which is added to the input sum, is a numerical value assigned to each of these neurons. The activation function, a threshold function, is then applied to this number. If a certain neuron is activated or not depends on the outcome of the activation function. Data is sent via the channels from an active neuron to the neurons in the next layer. This kind of data transmission via the network is known as "forward propagation." The neuron with the greatest value fires in the output layer, which decides the output. The numbers are essentially a probability. To identify the prediction error, the expected and actual outputs are compared. The size of the error provides a clue as to the kind and size of modification needed to reduce it. Then, this data is sent backward across our network. This process is called "back propagation." Now the weights are modified in light of this knowledge. With many inputs, this cycle of forward propagation and back propagation is carried out iteratively. This procedure is repeated until our weights are distributed so that, in the majority of cases, the network can correctly predict the type of tumour. Our training has now come to an end. Although NN may take hours or even months to train, the time investment is appropriate given the extent of the technology. Numerous studies demonstrate that, after pre-processing MRI data, CNN (Convolutional Neural Network), as opposed to Support Vector Machine (SVM) and Random Forest Field, was the most effective neural network classification system. less hardware requirements are needed, and processing huge size images (256 * 256) takes a reasonable amount of time. Furthermore, utilising the DNN classifier demonstrates great accuracy in comparison to conventional classifiers.

- Initial stage of processing
- Constructing and training different models
- Evaluation of each model's performance

IMPLEMENTATION

It entails six steps: obtaining an input image from the data collection, image pre-processing, image enhancement, binary thresholding image segmentation, and classification of brain tumours using convolutional neural networks. Following the completion of all the aforementioned procedures, the product is then scrutinised. Every module is distinctive in some manner. Every action has a purpose. A testing and training data set is also included in this design. Nearly 2000 photos make up the data set, which was downloaded from Kaggle and is used to train and test the system. The input image is first pre-processed with noise-filtering techniques such the median and bilateral filters, and then the Sobel filter is used to improve the image. The resultant image is then segmented using binary thresholding and subjected to morphological procedures. Convolutional Neural Network is used to classify the images and determine whether or not a tumour is present.



CONCLUSION AND FUTURE WORK

The most typical applications of MRI involve the segmentation and classification of tumours. Convolutional neural networks (CNN) have the benefit of learning representational complicated functions in both healthy brain tissues and malignant tissues directly from the multi-modal MRI images, but we prefer to improve its accuracy.

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