

Enhancing Road Safety with Machine Learningbased Pothole Detection

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Abstract: The goal of this project endeavours to enhance road safety through a machine learning-based pothole detection system. The primary objective is to develop an artificial intelligence solution that can accurately identify and analyse potholes on road surfaces, thereby contributing to proactive road maintenance and accident prevention. Employing advanced computer vision algorithms, the system focuses on detecting key features associated with potholes, utilizing joint point analysis for precise identification. Utilizing cutting-edge machine learning models, the program categorizes and classifies various pothole characteristics, ensuring comprehensive coverage of road conditions. The user-friendly interface of the system allows for seamless interaction, displaying detected potholes and providing specific information, such as their dimensions and potential impact on road safety. A key advantage of this AI pothole detection system lies in its ability to offer tailored feedback to users, facilitating prompt repairs and maintenance. By actively assisting in the identification and rectification of potholes, the technology transcends mere detection, significantly contributing to the overall improvement of road safety.

I. INTRODUCTION

"Pothole detection using machine learning" involves the application of artificial intelligence algorithms to automatically identify and assess the presence of potholes on road surfaces. This technology utilizes various data sources, such as images or sensor data, to train machine learning models capable of recognizing patterns associated with potholes.

The goal is to enable real-time monitoring, early detection, and proactive maintenance of road infrastructure to enhance overall road safety. In recent years, road safety has become a critical concern as traffic volumes continue to rise, posing challenges for both commuters and authorities. Potholes, in particular, contribute significantly to road hazards, causing accidents, vehicle damage, and disruptions to traffic flow. Traditional methods of pothole detection and repair are often time-consuming and reactive, leading to delays in addressing road hazards. The integration of machine learning (ML) techniques has emerged as a promising solution to enhance road safety, particularly in the context of pothole detection. ML algorithms can be trained to analyze data from various sources, including images, to automatically identify and assess the severity of potholes on road surfaces.

II. PROBLEM STATEMENT

Potholes have been a difficult issue and have become a danger for safe street travel, so as to beat the issue we are proposing this framework utilizing MI(Machine Learning) and Image Processing. which will recognize the potholes and by doing so we can proficiently handle the issue. Detecting potholes using machine learning presents a significant challenge in the realm of urban infrastructure management. The existing manual inspection processes for identifying and addressing potholes are time-consuming and often inefficient. The objective is to design and implement an accurate and efficient pothole detection system that leverages machine learning algorithms. This system should be capable of processing real-time data, including images, videos, or sensor inputs, to promptly identify and classify potholes in road surfaces. Key challenges include handling the variability in pothole characteristics, acquiring a diverse and well-labeled dataset for model training, ensuring real-time processing capabilities, addressing adverse environmental factors, seamlessly integrating with existing infrastructure, and achieving scalability for deployment across extensive road networks.

Objectives

Enhancing road safety with machine learning-based pothole detection serves several objectives:

Reduce Accidents: Identifying potholes in real-time helps drivers to avoid them, thereby reducing the chances of accidents caused by sudden swerving or loss of control.



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Prevent Damage to Vehicles: Potholes can cause significant damage to vehicles, including flat tires, bent rims, and suspension damage. By detecting potholes in advance, drivers can take necessary precautions, such as slowing down or changing lanes, to prevent vehicle damage.

Improve Road Maintenance: By collecting data on pothole locations and severity, authorities can prioritize road maintenance efforts more effectively. Machine learning algorithms can analyze this data to identify patterns and trends, helping authorities allocate resources efficiently to repair or prevent potholes in high-risk areas.

Enhance Road Infrastructure Planning: Data collected through machine learning-based pothole detection can also inform long-term infrastructure planning. By understanding where and why potholes form, authorities can design and construct roads more resilient to factors that contribute to pothole formation.

III. SYSTEM DESIGN

The chapter on system design is an important part of the system development process that focuses on the creation of a detailed plan for building system or product.



3.1 Architecture Diagram

User Interface (UI): The user interface (UI) serves as the entry point for users to interact with the application. It's built using Flask, a Python web framework known for its simplicity and ease of use. Upon accessing the application, users are presented with a user-friendly interface that allows them to perform actions such as registering a new account or logging in if they already have one.

Backend Processing: Once a user logs in, the backend processing of the application is managed by the Streamlit Framework. Streamlit is a Python library used for building interactive web applications for data science and machine learning tasks.

Pothole Detection (Image): When users upload an image, Streamlit sends the image data to the backend, where the YOLOv5 Algorithm processes it to detect potholes. YOLOv5 analyzes the image and identifies regions where potholes are present, providing results back to the user.



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Pothole Detection (Video): Similar to image detection, users can upload a video recording. Streamlit handles the video upload, and each frame of the video is sent to the backend for processing by the YOLOv5 Algorithm. in the video footage. processing by the YOLOv5 Algorithm. This allows for the detection of potholes over time in the video footage.

Results Display: After the pothole detection process is completed, the results are displayed to the user through the UI. The UI may present the detected potholes visually, such as overlaying bounding boxes or markers on the uploaded images or video frames to highlight the locations of detected potholes.

Use Case Diagram

A use case diagram depicts the interactions between actors (users or external systems and the system being considered. It demonstrates the various ways in which users caninteract with the system to accomplish specific goals or tasks.



5.2 Use Case Diagram

Flask-based UI: Flask is a lightweight web framework for Python. It allows developers tobuild web applications quickly and efficiently. Flask provides tools and libraries for handling HTTP requests, rendering HTML templates, and managing user sessions.

Register/Login: The registration and login functionalities allow users to create accounts and securely access the application. Flask manages user authentication, sessionmanagement, and password encryption to ensure the security of user accounts and data.

Backend Processing

Streamlit Framework: Streamlit is a Python library designed for building interactive webapplications for data science and machine learning tasks. It simplifies the process of creating web interfaces by allowing developers to write Python scripts that are automatically converted into interactive web apps.



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Pothole Detection (Image): Upon uploading an image for pothole detection, Streamlit sends the image data to the backend server. The backend server, powered by Streamlit, thenpasses the image data to the YOLOv5 Algorithm for processing.

Pothole Detection (Video): Similar to image detection, when a video is uploaded, Streamlit handles the video file and sends each frame to the backend server for processing.

Results Display: Once the pothole detection process is complete, the results are presented to the user through the Flaskbased UI. The results may include visual representations of detected potholes, such as bounding boxes or color-coded markers overlaid on the original images or video frames.

IV. RESULT ANALYSIS

The primary objective is to enhance road safety by detecting potholes using machine learning techniques. Specifically, the aim is to leverage the YOLOv5 algorithm for real- time pothole detection.



Figure 6.1: Home Page

In figure 6.1 shows the homepage serves as a central hub for users, offering an intuitive Access Portal where they can swiftly navigate to either login or register for an account.



Figure 6.2 Register Page





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In this fig 6.2 shows The Register page facilitates the initial steps of creating an account, guiding users through the process of setting up their credentials.

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Figure 6.3. Login Page

In this figure 6.3 shows the Login page acts as the gateway to accessing the user's account, requiring input of their designated username and password for authentication. their credentials into the respective fields, verifying their identity and granting access to the platform's features and content.

2	Pothole Detection	
	Select the type of upload:	
	O Photo	
	🔿 Video	
	Upload a photo	
	Drag and drop file here Limit 200MB per file + JPG, JPEG, PNG	Browse files

Figure 6.4: Interface for Pothole Detection

In this figure 6.4 describes Pothole Detection: Image & Video Selection. In pothole detection, users can upload images or videos via a browser interface to enable automated analysis.



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Figure 6.5: Detected Pothole using Images

In this figure 6.5 describes Pothole Detection: Image Analysis. In pothole detection using images, algorithms analyze the uploaded media to measure pothole sizes in meters.



Figure 6.6: Detected Pothole using Videos

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Figure 6.6 describes detecting potholes in videos using the YOLOv5 algorithm entails segmenting the video into individual frames and applying YOLOv5's object detection capabilities to each frame.



Figure 6.7: Dataset of Images

Figure 6.7 describes to effectively train and test a YOLOv5 algorithm for pothole detection, a diverse dataset of annotated images depicting various road conditions and pothole instances is crucial.



Figure 6.8: Dataset of Videos

Figure 6.8 describes training and testing the YOLOv5 algorithm for pothole detection in videos, a dataset comprising annotated videos is required.

V. CONCLUSION

In conclusion, the machine learning-based pothole detection systems presents a transformative opportunity to revolutionize road safety infrastructure. Through the fusion of cutting-edge algorithms like YOLOv5 with intuitive user interfaces built on frameworks such as Flask and Streamlit, this innovative approach stands poised to redefine how we perceive and mitigate road hazards. By harnessing the power of computer vision, these systems enable real-time, accurate identification of potholes across a spectrum of road conditions and environments.

Moreover, the deployment of such systems not only streamlines the detection process but also empowers stakeholders with actionable insights. Authorities can leverage the data generated by these systems to prioritize maintenance efforts, allocate resources more effectively, and ultimately enhance the resilience and longevity of road networks.

Furthermore, the integration of user- friendly interfaces ensures accessibility and engagement, fostering collaboration between communities and governing bodies in the shared goal of safer roads.

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